

General Relativity

Week 3

Last time:

If $p \in M$, tensors of type (k, l) over p :

$$T: \underbrace{T_p^* M \times T_p^* M \times \dots \times T_p^* M}_k \times \underbrace{T_p M \times \dots \times T_p M}_l \rightarrow \mathbb{R}$$

In local coordinates:

$$T = T_{\beta_1 \dots \beta_l}^{\alpha_1 \dots \alpha_k} \frac{\partial}{\partial x^{\alpha_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{\alpha_k}} \otimes dx^{\beta_1} \otimes \dots \otimes dx^{\beta_l} \quad \left| \quad \text{So, } T_{\beta_1 \dots \beta_l}^{\alpha_1 \dots \alpha_k} = T\left(\frac{\partial}{\partial x^{\beta_1}}, \dots, \frac{\partial}{\partial x^{\beta_l}}; dx^{\alpha_1}, \dots, dx^{\alpha_k}\right)\right.$$

Operations:

- Tensor product: $(T_1 \otimes T_2)_{\beta_1 \dots \beta_{l_1+l_2}}^{\alpha_1 \dots \alpha_{k_1+k_2}} = (T_1)_{\beta_1 \dots \beta_{l_1}}^{\alpha_1 \dots \alpha_{k_1}} \cdot (T_2)_{\beta_{l_1+1} \dots \beta_{l_1+l_2}}^{\alpha_{k_1+1} \dots \alpha_{k_1+k_2}}$
- Contraction. With respect to one contravariant and one covariant index (tr)

Ex: $1^{st} - 1^{st}$ indices:

$$\text{tr } T_{j_1 \dots j_{l-1}}^{\alpha_1 \dots \alpha_{k-1}} = T_{\alpha_{k-1} j_1 \dots j_{l-1}}^{\alpha_{k-1}}$$

Coordinate independent! Like the trace of a linear endomorphism

In fact: A linear map $L: T_p M \rightarrow T_p M$

can be viewed as a $(1,1)$ tensor $\tilde{L}: T_p^* M \times T_p M \rightarrow \mathbb{R}$

$$\text{So that } \tilde{L}(w, v) = w(L(v)) \Leftrightarrow L(v) = \tilde{L}(\cdot, v)$$

In general: $\tilde{L}: \underbrace{T_p^* M \times \dots \times T_p^* M}_k \times \underbrace{T_p M \times \dots \times T_p M}_l \rightarrow \mathbb{R}$

can be viewed as $L: \underbrace{T_p^* M \times \dots \times T_p^* M}_{k-l_1} \times \underbrace{T_p M \times \dots \times T_p M}_{l-l_1} \rightarrow \underbrace{\otimes^k T_p^* M}_{\otimes^{l-l_1} T_p M}$

So: If L is $(1,1)$: $\text{tr } L$ is the usual trace.

Example: If $\omega \in T_p^*M$, $v \in T_pM$:

$$(\omega \otimes v)_p^a = \omega_p v^a$$

$$\text{tr}(\omega \otimes v) = \omega_a v^a = \omega(v)$$

$$\text{tr}(\text{tr}(g \otimes X \otimes Y)) = g(X, Y)$$

$\nearrow$ metric
 $\nwarrow \nearrow$ vectors

Musical isomorphisms:

Let g be a non-degenerate symmetric $(0,2)$ tensor
(e.g. coming from Lorentzian inner product)

It defines a natural isomorphism between T_pM and T_p^*M
by $X \longrightarrow \omega = g(X, \cdot)$

In coordinates: $\omega_a = g_{ab} X^b$ $\leftarrow$ Musical isomorphism

$$\Leftrightarrow X^a = g^{ab} \omega_b$$

$\uparrow$ Inverse matrix of $[g]$!

More generally; I can raise - lower indices with g (i.e. changing the type of tensors). I will keep the same symbol for the new tensor

e.g. $T_{ab} = g_{ax} T_b^x$

I can extend g to inner product on tensor by

$$g(F, G) = g_{a_1 i_1} \dots g_{a_n i_n} g^{b_1 j_1} \dots g^{b_l j_l} F_{p_1 \dots p_l}^{a_1 \dots a_n} G_{j_1 \dots j_l}^{i_1 \dots i_n}$$

e.g. if w_1, w_2 are covectors:

$$g(w_1, w_2) = g^{ab} (w_1)_a (w_2)_b$$

The musical isomorphisms are isometries with respect to this (extended) inner product.

Tensor Fields

Def: T is a (smooth) tensor field of type (k, l)

if $\forall p \in M$, it is an assignment $p \longrightarrow T|_p \in \otimes^k T_p M \otimes^l T_p^* M$ with smooth components in any local coordinate chart.

Ex: Lorentzian metric g is a $(0, 2)$ tensor field.

Note: if $w_1, \dots, w_k \in \Gamma^*(M)$, $v_1, \dots, v_l \in \Gamma(M)$.

$T(w_1, \dots, w_k, v_1, \dots, v_l)|_p$ depends only on $w_i|_p, \dots$

So $T: \Gamma^*(M) \times \dots \times \Gamma^*(M) \times \Gamma(M) \times \dots \times \Gamma(M) \longrightarrow C^\infty(M)$

is $C^\infty(M)$ -multilinear!

$$T(f \cdot w_1, \dots) = f \cdot T(w_1, \dots)$$

Theorem: A map $T: \Gamma^*(M) \times \dots \times \Gamma^*(M) \times \Gamma(M) \times \dots \times \Gamma(M) \longrightarrow C^\infty(M)$ is a tensor field if and only if it is $C^\infty(M)$ -multilinear

Ex: On $\mathbb{R}^n$: $\text{div}: \Gamma(\mathbb{R}^n) \rightarrow C^\infty(\mathbb{R}^n)$
is not a tensor field.

Lie brackets and flows:

Let $X \in \Gamma(M)$. It is a first order differential operator

$X: C^\infty(M) \rightarrow C^\infty(M)$. In local coordinates: $X = X^a \frac{\partial}{\partial x^a}$

For $X, Y \in \Gamma(M)$: The composition $X \cdot Y$ is a 2nd order diff. operator

But $[X, Y] = X \cdot Y - Y \cdot X$ is 1st order

In local coordinates:

$$[X, Y]^a = X^b \frac{\partial}{\partial x^b} Y^a - Y^b \frac{\partial}{\partial x^b} X^a$$

Commutator or Lie-bracket

Properties: 1) $[X, Y] = -[Y, X]$ (anticommutativity)

2) $\mathbb{R}$ -bilinear

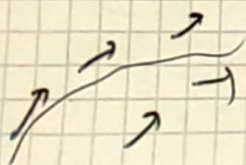
3) Jacobi's identity: $[[X, Y], Z] + [[Z, X], Y] + [[Y, Z], X] = 0$

So $(\Gamma(M), [\cdot, \cdot])$ forms a Lie algebra.

Of which group?

Def: Let $X \in \Gamma(M)$. Integral curve of X : $\gamma: (a, b) \rightarrow M$,

$$\dot{\gamma}(t) = X|_{\gamma(t)} \quad \forall t \in (a, b)$$



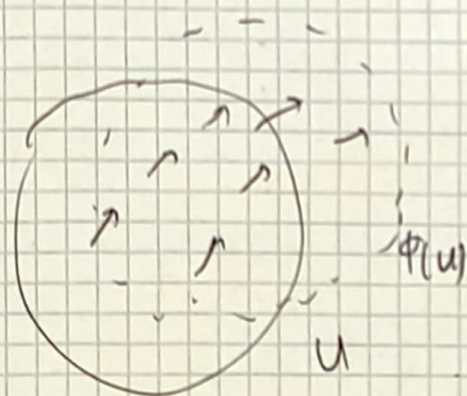
In local coordinate: $\dot{y}^p(t) = X^p(y(t))$
 $\uparrow$ 1st order ODE

Fundamental theorem of ODEs:

The initial value problem $\begin{cases} \dot{y} = F(t, y) \\ y(0) = y_0 \end{cases}$ has a unique solution

(as long as F is regular enough) depending smoothly on the initial data.

Theorem: Let $X \in \mathcal{X}(M)$. $\forall U \subseteq M$ open such that $\bar{U} \subset\subset M$
 (i.e. U is pre-compact), ~~flow map~~



~~flow map~~ $\exists \delta > 0$ and a
 unique flow map $\phi: (-\delta, \delta) \times U \rightarrow M$
 $\uparrow$ smooth $\uparrow$ $\uparrow$
 associated to X , i.e.

$$1) \phi(0, x) = x$$

$$2) \frac{\partial}{\partial t} \phi(t, x) = X(\phi(t, x)).$$

So ϕ : Moves U along the integral curve of X

Note: If X is compactly supported: $\delta = +\infty$, ϕ extends
 to $(-\infty, +\infty) \times M$

We will denote $\phi(t, \cdot)$ by $\phi_t(\cdot)$

$\{\phi_t\}_{t \in \mathbb{R}}$: Flow of local diffeomorphisms generated by X

1-parameter group: $\phi_t \circ \phi_s = \phi_{t+s}$

$\text{Diff}_{\text{con}}(M)$: Has Lie algebra ~~isom~~ $T_{\text{con}}(M)$

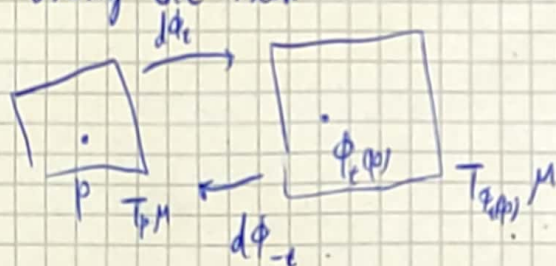
Ex: • If $\bar{X} = \frac{\partial}{\partial x^1}$: $\Phi_t(x^1, x^2, \dots, x^n) = (x^1 + t, x^2, \dots, x^n)$

$\begin{matrix} \rightarrow & \rightarrow & \rightarrow \\ \rightarrow & \rightarrow & \rightarrow \end{matrix}$

• On $\mathbb{R}$: $X = y^2 \frac{d}{dy}$ has finite time of existence
($\dot{y} = y^2$)

Lie derivative:

Derivative along the flow



Definition

1) If $f \in C^\infty(M)$: $L_X f|_p = \lim_{t \rightarrow 0} \frac{f(\Phi_t(p)) - f(p)}{t}$

2) If $Y \in T(M)$: $L_X Y|_p = \lim_{t \rightarrow 0} \frac{d\Phi_{-t}(Y|_{\Phi_t(p)}) - Y|_p}{t}$

3) If $\omega \in T^*(M)$: $L_X \omega|_p = \lim_{t \rightarrow 0} \frac{\overset{\text{pull-back}}{\Phi_t^*}(\omega|_{\Phi_t(p)}) - \omega|_p}{t}$

4) For higher order tensors.

Extend by linearity and the condition that

$$L_X (F \otimes G) = (L_X F) \otimes G + F \otimes (L_X G)$$

Rule: This way: L_X commutes with contractions

Theorem: 1) $L_X f = X(f)$
 2) $L_X Y = [X, Y]$
 @ ~~QED~~

Proof: • At a point where $X|_p \neq 0$: choose local coordinates

Where $X = \frac{\partial}{\partial x^1}$

Then Φ_t : translation in the x^1 variable

Remark: Since we want to prove a coordinate-independent statement, it suffices to show it in one coordinate system

From the definitions:

$$L_X f = \frac{\partial f}{\partial x^1}$$

$$(L_X Y)^k = \frac{\partial Y^k}{\partial x^1}$$

• At a point p where $X \neq 0$ on a neighborhood of p :

$$\Phi_t \equiv \text{id} \text{ there} \Rightarrow L_X f = 0, L_X Y = 0$$

• Any other point: Lies at the closure of the previous region, so by continuity we get the result $\square$

If g is a $(0,2)$ tensor:

$$L_X g = \lim_{t \rightarrow 0} \frac{\Phi_t^* g - g}{t}$$

So if g is a Lor. metric:

$$L_X g = 0 \Leftrightarrow \Phi_t^{(X)} \text{ is an isometry}$$

Such an X : Killing field

Note: $X(g(y,z)) = \underbrace{(L_X g)}_{\text{tr}(\text{tr}(g \otimes X))}(y,z) + g(L_X y, z) + g(y, L_X z)$

- If X generates a group of conformal isometries:

$$L_X g = h \cdot g \quad \text{for some } h \in C^\infty(M)$$

Example: On Minkowski space-time $(\mathbb{R}^{n+1}, \eta)$:

Killing vector fields:

- Translations $\frac{\partial}{\partial x^a}$, $a = 0, \dots, n$
- Rotations $\Omega_{ij} = x^i \frac{\partial}{\partial x^j} - x^j \frac{\partial}{\partial x^i}$, $i, j = 1, \dots, n$
- Boosts $\Omega_{0i} = x^0 \frac{\partial}{\partial x^i} + x^i \frac{\partial}{\partial x^0}$



↖ "Hyperbolic Rotation"

~~Conformal Killing fields on Minkowski:~~ $(n \geq 2)$

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